

STMicroelectronics LIG University of Grenoble





# Programming-Model Centric Debugging for Multicore Embedded Systems

### Kevin Pouget

Under the supervision of:

Dr. Miguel Santana, *STMicroelectronics* Prof. Jean-François Méhaut, *CEA/UJF* 



#### STMICROELECTRONICS, UNIVERSITY OF GRENOBLE/LIG LABORATORY

### Introduction

Embedded Systems and MPSoC

## Embedded Systems

(IEEE '92)

A computer system that is part of a larger system and performs some of the requirements of that system.

Embedded Systems and MPSoC

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### Consumer Electronics Devices

- 4K digital televisions
- Smartphones
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  - Augmented reality
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  - ⇒ high performance expectations.



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- High-level development methodologies
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  - Programming models & environments
- Efficient verification & validation tools
  - Our research effort

Verification & Validation

### Important domain for business, engineering and research

- Time-to-market
- Consumer experience
- Costly maintenance phase





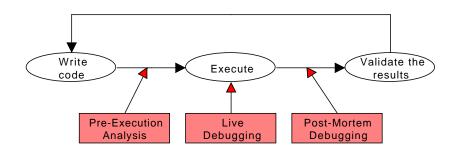


Verification & Validation

## Important domain for business, engineering and research

- Time-to-market
- Consumer experience
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- Time and nerves consuming
- Large set of skills/techniques involved
- Still imperfect



## Agenda

1 Background: MPSoC Programming and Debugging

2 Programming Model Centric Interactive Debugging

McGDB Case-Studies

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### MultiProcessor System-on-Chip

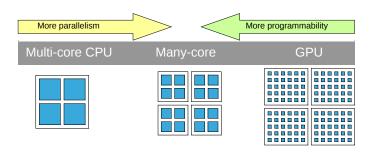
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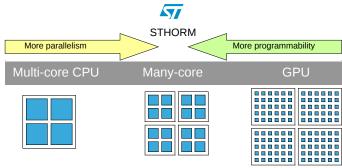




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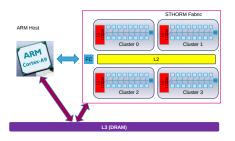
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### STHORM Platform — our reference MPSoC

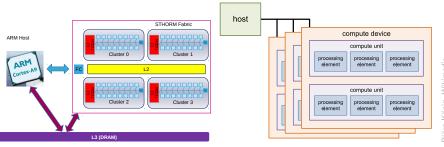
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- CPU + 4 clusters × 16 lightweight/energy-efficient cores
  - ullet dedicated hardware accelerators



MPSoC and GPU Systems

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- ST Heterogeneous Low-Power Many-core (Platform 2012)
- CPU + 4 clusters × 16 lightweight/energy-efficient cores
  - ± dedicated hardware accelerators
- GPU-like architecture



# Background: MPSoC Programming and Debugging MPSoCs and Programming Models

How to program such complex architectures?

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How to program such complex architectures? **Programming models and environments!** 

MPSoCs and Programming Models

... not so many clear definitions in the literature, so ...

## Programming Model

(Skillicorn and Talia '98)

- A model is an abstract machine...
- providing certain operations to the programming level above and ...
- requiring implementations for each of these operations on all of the architectures below.

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- runtime libraries
- APIs

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Application

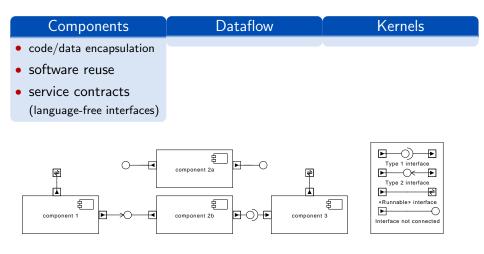
Supportive
Environment
(Abstract Machine)

Real machine

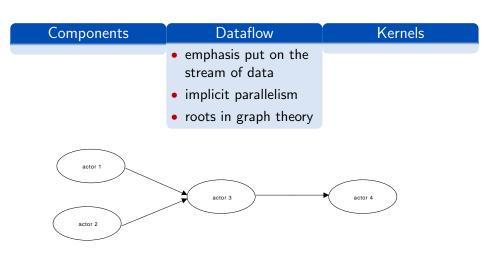
Programming Models for  $\operatorname{STHORM}$  MPSoC

Components Dataflow Kernels

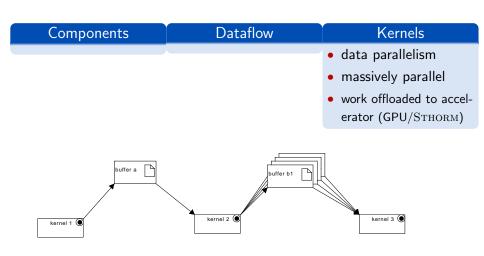
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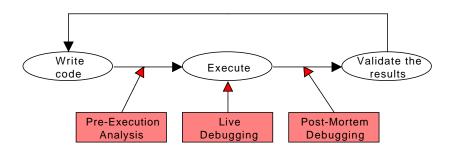
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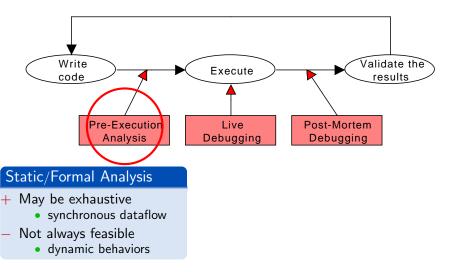


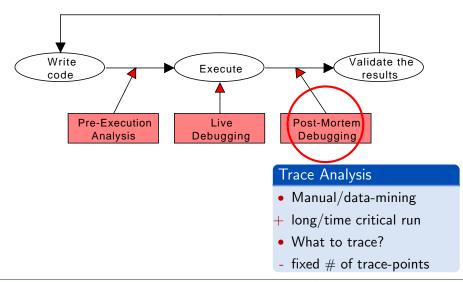
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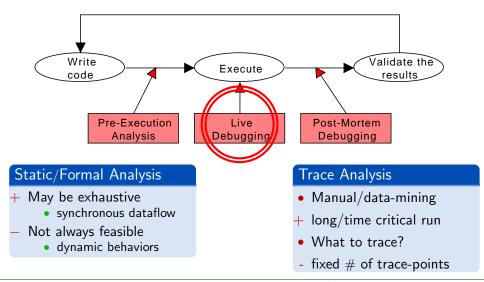
Components	Dataflow	Kernels
• code/data encapsulation	<ul> <li>emphasis put on the</li> </ul>	<ul> <li>data parallelism</li> </ul>
• software reuse	stream of data	<ul> <li>massively parallel</li> </ul>
<ul> <li>service contracts</li> </ul>	<ul> <li>implicit parallelism</li> </ul>	• work offloaded to accel-
(language-free interfaces)	• roots in graph theory	erator (GPU/STHORM)

Different models covering large programming domain ... but what about Verification & Validation? correctness guarantees vs. development constraints ...









Tools and Techniques, Advantages of Interactive Debugging

#### Interactive Debugging

- Developers mental representation VS. actual execution
- Understand the different steps of the execution

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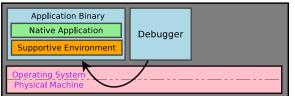
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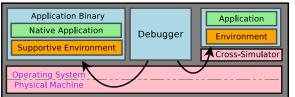
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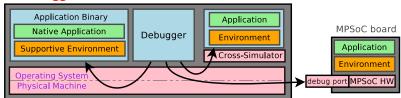
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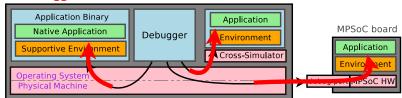
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#### **Objective**

Provide developers with means to

better understand the state of the high-level applications
and control more easily their execution,
suitable for various models and environments.

### Agenda

1 Background: MPSoC Programming and Debugging

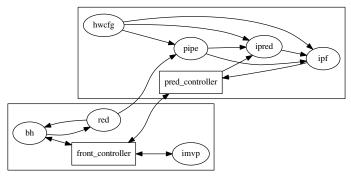
Programming Model Centric Interactive Debugging

3 MCGDB Case-Studies

Idea: Integrate programming model concepts in interactive debugging

#### Provide a Structural Representation

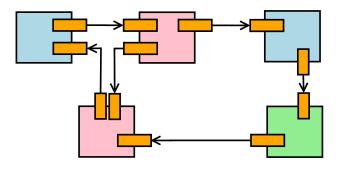
- Draw application architecture diagrams
- Represent the relationship between the entities
- Offer catchpoints on architecture-related operations



Graph of a dataflow from the case-study

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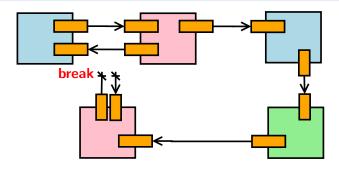
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Reconfiguration of an application based on components

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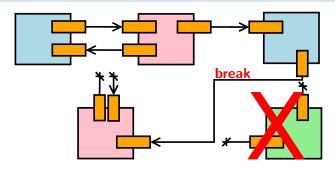
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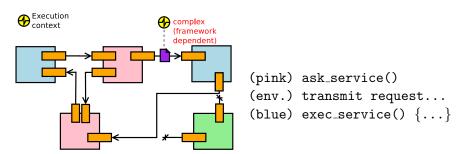
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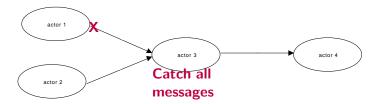


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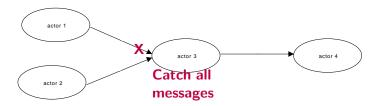
- Monitor the collaboration between the tasks
- Detect communication, synchronization events
  - interpret their pattern and semantics (one-to-one, one-to-many, global or local barriers)
- Offer communication-aware catchpoint mechanisms



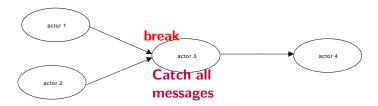
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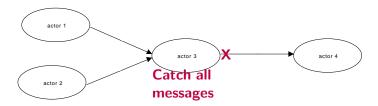
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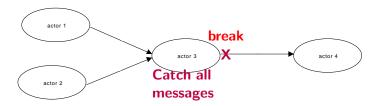
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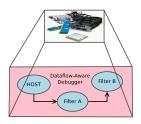


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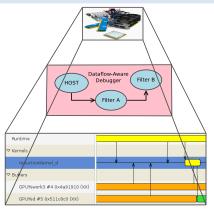
#### 3 Interact with the Abstract Machine

- Recognize the different entities of the model
- Provide details about their state, schedulability, callstack, ...
- Provide support to understand how they reached their current state



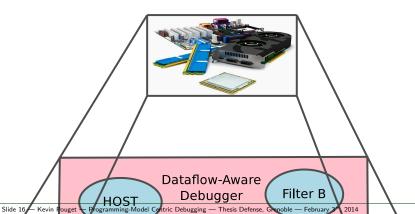
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#### 3 Interact with the (abstract) Machine

- Support interactions with *real* machine
  - memory and processor inspection
  - breakpoints and watchpoints (maybe per entity)
  - step-by-step execution . . .

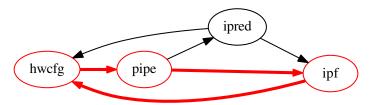


#### 4 Open Up to Model and Environment Specific Features

- Follow messages over *multiple* entities
- User-defined constraints on the graph topology
- Deadlock detection in task-based models

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cycles in the graph of blocking communications  $\Longrightarrow$  deadlock

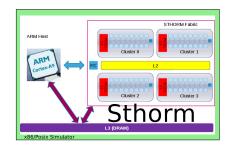
- 1 Provide a Structural Representation
- 2 Monitor Dynamic Behaviors
- 3 Interact with the Abstract Machine
- Open Up to Model and Environment Specific Features

Proof-of-concept Environment

#### STHORM / Platform 2012

ST/CEA MPSoC research platform

• x86 platform simulators



Proof-of-concept Environment

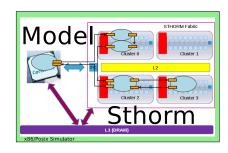
#### STHORM Progr. Environments

- Components (NPM)
- Dataflow (PEDF)
- Kernel (OpenCL)

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Proof-of-concept Environment

#### The GNU Debugger

- Adapted to low level/C debugging
- Large user community

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Model

Proof-of-concept Environment

#### The GNU Debugger

- Adapted to low level/C debugging
- Large user community
- Extendable with Python API

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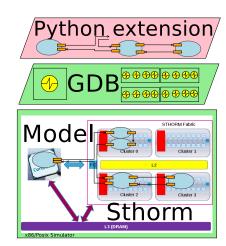
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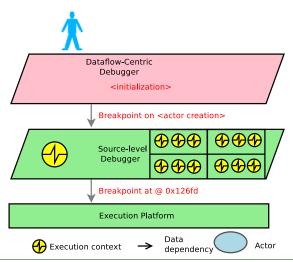
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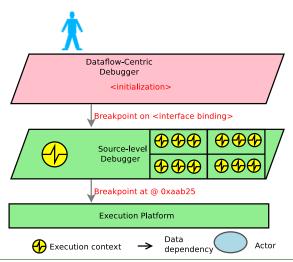


Interpreting Execution Events

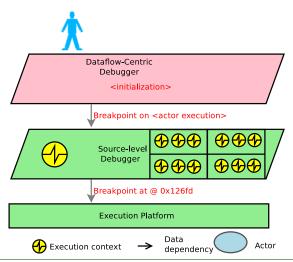
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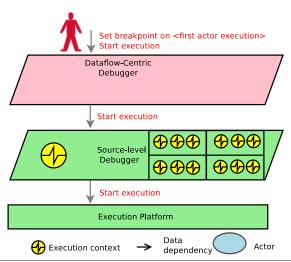
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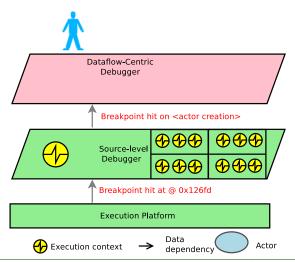
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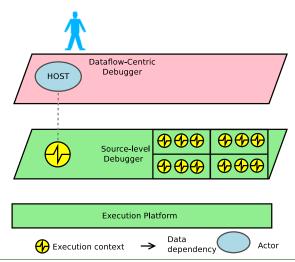
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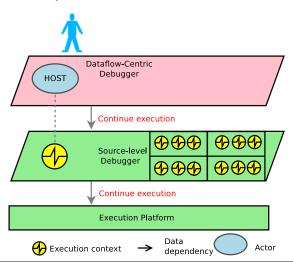
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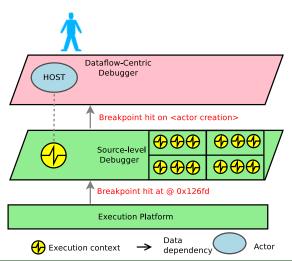
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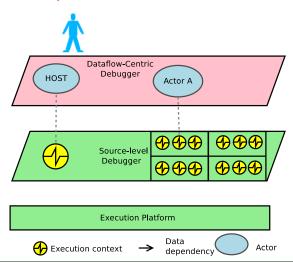
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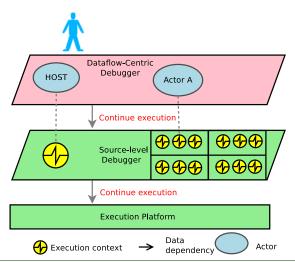
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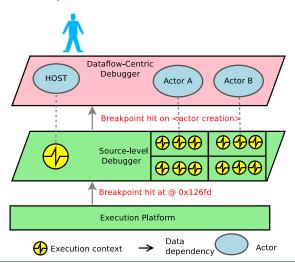
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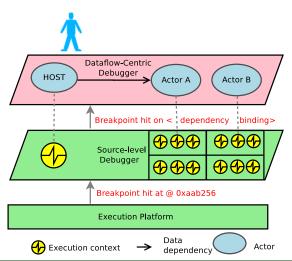
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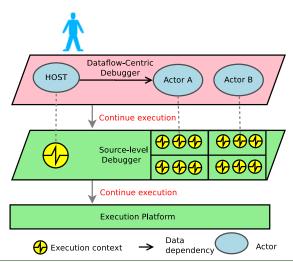
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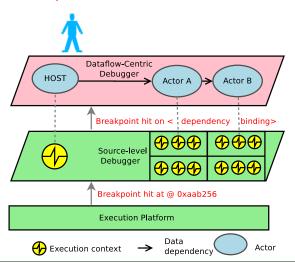
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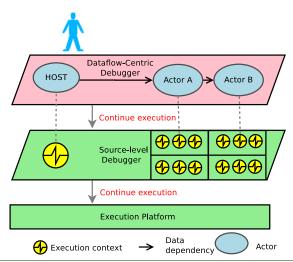
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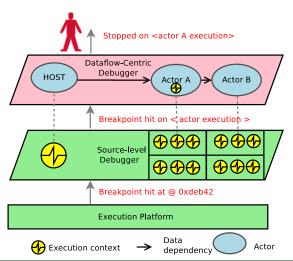
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Interpreting Execution Events



Capture Mechanism Evaluation and Alternatives

Application  Debugger  Supportive Environment	Breakpoints and Debug Information	
Capturable Info.	High	
Execution Overhead	Significant	
Cooperation btw. Debug and Env.	None	
Portability	Low	

Capture Mechanism Evaluation and Alternatives

Application Preloaded lib  Supportive Environment	Breakpoints and Debug Information	Preloaded Library
Capturable Info.	High	Limited to API
Execution Overhead	Significant	Limited
Cooperation btw. Debug and Env.	None	Low
Portability	Low	Very Good

Capture Mechanism Evaluation and Alternatives

Debugger Debug Debugger Supportive Environment	Breakpoints and Debug Information	Preloaded Library	Specialized Debug Module
Capturable Info.	High	Limited to API	Full
Execution Overhead	Significant	Limited	Limited
Cooperation btw. Debug and Env.	None	Low	Strong
Portability	Low	Very Good	Vendor Specific

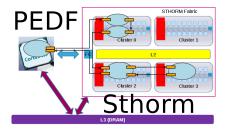
# Agenda

1 Background: MPSoC Programming and Debugging

2 Programming Model Centric Interactive Debugging

McGDB Case-Studies

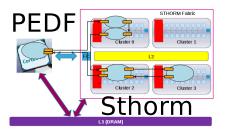
A PEDF Dataflow H.264 Video Decoder



#### Dataflow Environment (PEDF)

- Dynamic dataflow programming
- Good for multimedia application
- No verification/validation help
- Heterogeneous computing:
  - actors ⇒ HW accelerators

A PEDF Dataflow H.264 Video Decoder





# Dataflow Environment (PEDF)

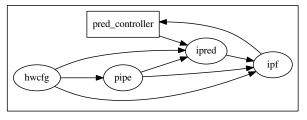
- Dynamic dataflow programming
- Good for multimedia application
- No verification/validation help
- Heterogeneous computing:
  - actors ⇒ HW accelerators

- Flexible video decoding standard
  - for HD television, blu-ray disks, broadcast, telephony, . . .
- Good dataflow decomposition
- Developed to validate PEDF design

# MCGDB Case-Studies: A PEDF Dataflow H.264 Video Decoder

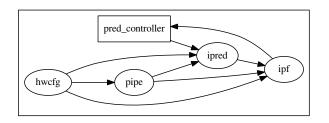
# The application is frozen, how can GDB help us?

hint: not much!



(static graph provided by the compiler)

# MCGDB Case-Studies: A PEDF Dataflow H.264 Video Decoder The application is frozen, how can GDB help us?

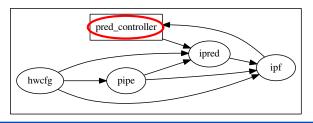


# (gdb) info threads

Id Target Id Frame
 1 Thread 0xf7e77b 0xf7ffd430 in \_\_kernel\_vsyscall ()
\* 2 Thread 0xf7e797 operator= (val=..., this=0xa0a1330)

# $\operatorname{MCGDB}$ Case-Studies: A PEDF Dataflow H.264 Video Decoder

# The application is frozen, how can GDB help us?



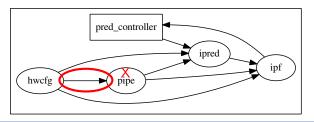
# (gdb) thread apply all where

```
Thread 1 (Thread 0xf7e77b):
#0  0xf7ffd430 in __kernel_vsyscall ()
#1  0xf7fcd18c in pthread_cond_wait@ ()
#2  0x0809748f in wait_for_step_completion(struct... *)
#3  0x0809596e in pred_controller_work_function()
#4  0x08095cbc in entry(int, char**) ()
#5  0x0809740a in host_launcher_entry_point ()
```

Slide 23 — Kevin Pouget — Programming-Model Centric Debugging — Thesis Defense, Grenoble — February 3<sup>rd</sup>, 2014

# $\operatorname{MCGDB}$ Case-Studies: A PEDF Dataflow H.264 Video Decoder

#### The application is frozen, how can GDB help us?



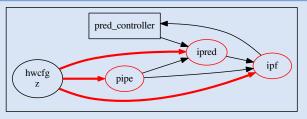
# (gdb) thread apply all where

Slide 23 — Kevin Pouget — Programming-Model Centric Debugging — Thesis Defense, Grenoble — February 3<sup>rd</sup>, 2014

# MCGDB Case-Studies: A PEDF Dataflow H.264 Video Decoder

The application is frozen, how can mcGDB help us?

# (mcgdb) info graph

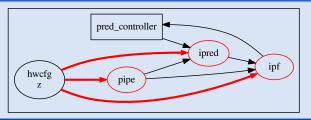


- pipe, ipred and ipf are blocked
- hwcfg is asleep

# ${ m MCGDB}$ Case-Studies: A PEDF Dataflow H.264 Video Decoder

The application is frozen, how can mcGDB help us?

# (mcgdb) info graph



# (mcgdb) info actors +state

```
#0 Controller 'pred_controller':
    Blocked, waiting for step completion
#1/2/3 Actor 'pipe/ipref/ipf':
```

Blocked, reading from #4 'hwcfg'

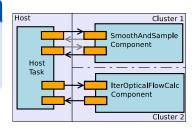
#4 Actor 'hwcfg':

Asleep, Step completed

A Feature Tracker Based on NPM Components

# Component Framework (NPM)

- Low-level access to STHORM architecture
- Optimized communication components
- ullet 1 component per cluster and fork-join //



A Feature Tracker Based on NPM Components

# Component Framework (NPM)

- Low-level access to STHORM architecture
- Optimized communication components
- 1 component per cluster and fork-join //

# Host Cluster 1 SmoothAndSample Component Host Task IterOpticalFlowCalc Component Cluster 2

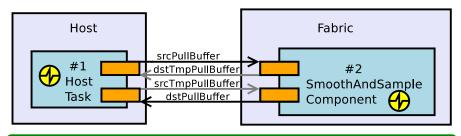
#### PKLT Feature Tracker

- Track interesting features btw. frames
- Part of an augmented reality application





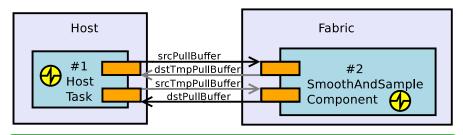
A Feature Tracker Based on NPM Components



# (mcgdb) info component 2 +interfaces +counts

#2 Component[SmoothAndSampleComponent.so]
srcPullBuffer #35 msgs
dstTmpPushBuffer #36 msgs
srcTmpPullBuffer #35 msgs
dstPushBuffer #34 msgs

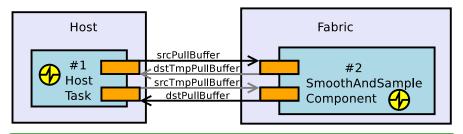
A Feature Tracker Based on NPM Components



# (mcgdb) info component 2 +interfaces +counts

```
#2 Component[SmoothAndSampleComponent.so]
srcPullBuffer #35 msgs
dstTmpPushBuffer #36 msgs
srcTmpPullBuffer #35 msgs
dstPushBuffer #34 msgs
```

A Feature Tracker Based on NPM Components



# (mcgdb) info component 2 +interfaces +counts

```
#2 Component[SmoothAndSampleComponent.so]
srcPullBuffer #35 msgs
dstTmpPushBuffer #36 msgs
srcTmpPullBuffer #35 msgs
dstPushBuffer #34 msgs
```

• that was a bug of the application! (msg sent to the wrong interface)

A Feature Tracker Based on NPM Components

# Excerpt from a 300-line-of-code file

```
/* Compute last lines if necessary */
if (tmp_size > 0) {
    ...
    /* Transmit the last lines computed */
    CALL(srcTmpPullBuffer, release)(...);
    CALL(dstTmpPushBuffer, push)(...);
}
```

OpenCL and BigDFT Kernel Programming



#### Kernel Programming Standard

(no environment distinction for us)

 Running on STHORM, but primarily used with GPU

OpenCL and BigDFT Kernel Programming



#### Kernel Programming Standard

(no environment distinction for us)

- Running on STHORM, but primarily used with GPU
- MC debugging only on host-side

OpenCL and BigDFT Kernel Programming





**BigDFT** 

#### Kernel Programming Standard

(no environment distinction for us)

- Running on STHORM, but primarily used with GPU
- MC debugging only on host-side

Density functional theory solver based on Daubechies wavelets. (electronic structure calculations)

- High performance requirements
- Hybrid CPU/GPU computing
- MPI OpenCL (Fortran / C)

OpenCL and BigDFT Kernel Programming

#### Generic OpenCL skeleton

```
cl_kernel ker = clCreateKernel(...);
cl_buffer buf = clCreateBuffer(...);
clSetKernelArg(ker, 0, buf, ...);
clSetKernelArg(ker, 1, N, ...);
clEnqueueNDRangeKernel(ker, ...);
clEnqueueReadBuffer(buf, ...);
```

That's common operations found in any OpenCL code ...

OpenCL and BigDFT Kernel Programming: Architecture Representation So let's instrument these events ...

```
cl_program clCreateProgramWithSource (context, code, ...);
cl_kernel clCreateKernel (program, kernel_name, ..);

cl_int clSetKernelArg (kernel, arg_index,..., arg_val);
cl_int clEnqueueNDRangeKernel (cmd_q, kernel, work_dim);

cl_mem clCreateBuffer (context, size, host_ptr, ..);
cl_int clEnqueueReadBuffer (cmd_q, buf, ..., ptr, ...);
```

OpenCL and BigDFT Kernel Programming: Architecture Representation So let's instrument these events ...

```
cl_program clCreateProgramWithSource (context, code, ...);
cl_kernel clCreateKernel (program, kernel_name, ..);

cl_int clSetKernelArg (kernel, arg_index,..., arg_val);
cl_int clEnqueueNDRangeKernel (cmd_q, kernel, work_dim);

cl_mem clCreateBuffer (context, size, host_ptr, ..);
cl_int clEnqueueReadBuffer (cmd_q, buf, ..., ptr, ...);
```

... to implement model-centric debugging commands:

```
(mcgdb) info programs
(mcgdb) info kernels [name|ID] {+where|+params}
(mcgdb) info buffers [ID] {+where|+params}
```

OpenCL and BigDFT Kernel Programming: Architecture Representation

So let's instrument these events ...

```
cl_program clCreateProgramWithSource (context, code, ...);
cl_kernel clCreateKernel (program, kernel_name, ..);

cl_int clSetKernelArg (kernel, arg_index,..., arg_val);
cl_int clEnqueueNDRangeKernel (cmd_q, kernel, work_dim);

cl_mem clCreateBuffer (context, size, host_ptr, ..);
cl_int clEnqueueReadBuffer (cmd_q, buf, ..., ptr, ...);
```

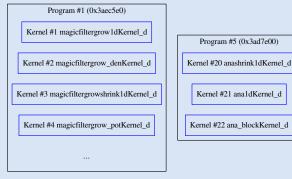
... to implement model-centric debugging commands:

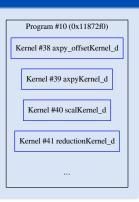
```
(mcgdb) info programs
(mcgdb) info kernels [name|ID] {+where|+params}
(mcgdb) info buffers [ID] {+where|+params}

(mcgdb) kernel [name|ID] catch {all|enqueue|set_arg|...}
(mcgdb) buffer [ID] catch {all|transfer|read|write|...}
```

OpenCL and BigDFT Kernel Programming: Architecture Representation

## (mcgdb) info programs +kernels





OpenCL and BigDFT Kernel Programming: Architecture Representation

(mcgdb) info programs +kernels

```
(mcgdb) info kernels 41 +where +use_count +handle
```

```
Kernel #41 reductionKernel_d
Creation stack:
  #0 0x0912a13 in create_reduction_kernels (...)
  #1 0x0900a10 in create_kernels (...)
  #2 0x0902744 in ocl_create_command_queue_id_ (...)
Use count: 5
Handle: (cl_kernel) 0x3aea590
```

OpenCL and BigDFT Kernel Programming: Architecture Representation

(mcgdb) info programs +kernels

```
(mcgdb) info kernels 41 +where +use_count +handle
```

```
Kernel #41 reductionKernel_d
Creation stack:
  #0 0x0912a13 in create_reduction_kernels (...)
  #1 0x0900a10 in create_kernels (...)
  #2 0x0902744 in ocl_create_command_queue_id_ (...)
Use count: 5
Handle: (cl_kernel) 0x3aea590
```

cl\_kernel kernel = 0x3aea590 = ... ; //somewhere in the code

 $$1 = (cl\_kernel) 0x3ae9d50$  $$2 = \langle incomplete type \rangle$ 

OpenCL and BigDFT Kernel Programming: Architecture Representation

```
(mcgdb) info kernels 41 +where +use_count +handle
Kernel #41 reductionKernel_d
  Creation stack:
    #0 0x0912a13 in create_reduction_kernels (...)
    #1 0x0900a10 in create_kernels (...)
    #2 0x0902744 in ocl_create_command_queue_id_ (...)
  Use count: 5
  Handle: (cl_kernel) 0x3aea590
cl_kernel kernel = 0x3aea590 = ... ; //somewhere in the code
(gdb) print kernel, print *kernel **native support**
```

OpenCL and BigDFT Kernel Programming: Architecture Representation

```
(mcgdb) info kernels 41 +where +use_count +handle
```

```
Kernel #41 reductionKernel_d
  Creation stack:
    #0 0x0912a13 in create_reduction_kernels (...)
    #1 0x0900a10 in create_kernels (...)
    #2 0x0902744 in ocl_create_command_queue_id_ (...)
    Use count: 5
    Handle: (cl_kernel) 0x3aea590
```

```
cl\_kernel\ kernel\ =\ 0x3aea590\ =\ \dots ; //somewhere in the code
```

## (mcgdb) info kernels +handle=0x3aea590

Kernel #41 reductionKernel\_d

```
Creation stack: (++ with GDB 7.6 ... pretty printers)
```

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## MCGDB Case-Studies

OpenCL and BigDFT Kernel Programming: Why Execution Visualization ?

Why Execution Visualization ?

let's consider an example ...

OpenCL and BigDFT Kernel Programming: Why Execution Visualization?

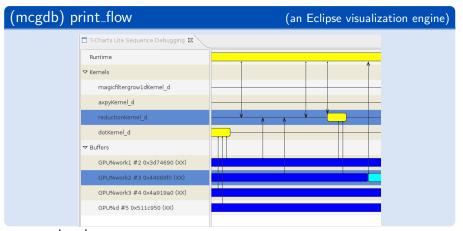
```
C code
```

```
reductionKernel (int n, double *in, double *out){...}
checkStatus(int *ptr, char *msg) { if(ptr == 0) exit(-1);}
void main()
 double *in = malloc(...) ; checkStatus(in, "in failed");
 double *out = malloc(...); checkStatus(out, "out failed");
 initialize(in);
reductionKernel(N, in, out);
// free ...
```

OpenCL and BigDFT Kernel Programming: Why Execution Visualization ? or in one page:

```
/* Instantiate the runtime */
command gueue = clCreateCommandQueue((*context)->context, aDevices[0], 0, &ciErrNum);
kerns->reduction_kernel_d=clCreateKernel(reductionProgram, "reductionKernel_d",&ciErrNum);
oclErrorCheck(ciErrNum, "Failed to create kernel!"):
/* Allocate the buffers on the GPU.
*buff_ptr = clCreateBuffer((*context)->context, CL_MEM_READ_ONLY, *size, NULL, &ciErrNum);
oclErrorCheck(ciErrNum, "Failed to create read buffer!");
/* Push the initial values to the GPU memory. */
cl_int ciErrNum = clEnqueueWriteBuffer((*command_queue)->command_queue, *buffer, CL_TRUE, 0, *size, p...
oclErrorCheck(ciErrNum, "Failed to enqueue write buffer!");
/* Set the kernel parameters. */
clSetKernelArg(kernel, i++,sizeof(*ndat), (void*)ndat); clSetKernelArg(kernel, i++,sizeof(*in), (void*...
clSetKernelArg(kernel, i++,sizeof(*out), (void*)out); clSetKernelArg(kernel, i++,sizeof(cl_dbl)*blk_...
/* Trigger the kernel execution. */
size t localWorkSize[] = { block size i }:
size_t globalWorkSize[] ={ roundUp(blk_size_i*2,*ndat)/2 };
ciErrNum = clEnqueueNDRangeKernel(command_queue->command_queue, kernel, 1, NULL, globalWorkSz, localWo...
oclErrorCheck(errNum, "Failed to enqueue reduction kernel!"):
/* Get the result back. */
cl int ciErrNum = clEngueueReadBuffer((*command gueue)->command gueue, *input, CL TRUE, 0, sizeof(cl d...
oclErrorCheck(ciErrNum, "Failed to enqueue read buffer!");
/* Then release the memory ... */
```

OpenCL and BigDFT Kernel Programming: Execution Visualization



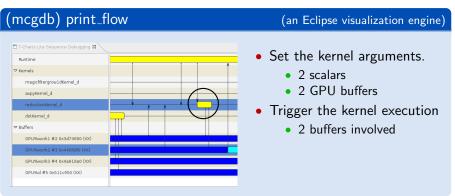
- updated on user request, or
- automatically on execution stops, step-by-step, ...

OpenCL and BigDFT Kernel Programming: Execution Visualization

#### (mcgdb) print\_flow (an Eclipse visualization engine) □ T-Charts Lite Sequence Debugging 🛭 Set the kernel arguments. Buntime ✓ Kernels 2 scalars magicfiltergrow1dKernel\_d 2 GPU buffers axpvKernel d dotKernel d GPU%work1 #2 0x3d74690 (XX) GDI Réwork3 #4 0v4aq19a0 (YY) GPU%d #5 0x511c950 (XX)

```
clSetKernelArg(kernel, i++, sizeof(*ndat),(void*)ndat);
clSetKernelArg(kernel, i++, sizeof(*in), (void*)in);
clSetKernelArg(kernel, i++, sizeof(*out), (void*)out);
clSetKernelArg(kernel, i++, sizeof(*sz), (void*)sz);
```

OpenCL and BigDFT Kernel Programming: Execution Visualization



OpenCL and BigDFT Kernel Programming: Execution Visualization

#### (mcgdb) print\_flow □ T-Charts Lite Sequence Debugging X Buntime ✓ Kernels 2 scalars magicfiltergrowldKernel d axpvKernel d dotKernel d → Buffers GPU%work1 #2 0x3d74690 (XX) GDI Réwork3 #4 0v4aq19a0 (YY) GPU%d #5 0x511c950 (XX)

(an Eclipse visualization engine)

- Set the kernel arguments.

  - 2 GPU buffers
- Trigger the kernel execution
  - 2 buffers involved
- Retrieve the result
  - buffer content is saved

```
cl_int ciErrNum = clEnqueueReadBuffer(
                     (*command_queue) -> command_queue,
                    *input, CL_TRUE, 0, sizeof(cl_double),
                    out, O, NULL, NULL);
```

Agenda

**Conclusions and Future Work** 

### Conclusions and Future Work

- Debugging high-level applications is challenging
- Lack of information about programming models and frameworks

## Our contribution: model-centric interactive debugging, applied to

- Component-software engineering (Scopes '12)
- Dataflow programming (SAC and HIPS '13)
- Kernels for accelerator programming

## Conclusions and Future Work

- Debugging high-level applications is challenging
- Lack of information about programming models and frameworks

## Our contribution: model-centric interactive debugging, applied to

- Component-software engineering (Scopes '12)
- Dataflow programming (SAC and HIPS '13)
- Kernels for accelerator programming

### **Proof-of-concept:** MCGDB, a prototype for STHORM platform

- Extends GDB and its Python interface:
  - Framework for model-centric debugging
  - Interface patches contributed to the community
- Usage studied through embedded and scientific applications

## Conclusions and Future Work

## Perspectives with programming-model centric debugging:

- Industrial side
  - Strengthen the implementation for production
  - Conduct extensive impact studies
  - Integrate within graphical debugging and visualization environments
- Research side
  - · Apply to different programming models
    - multi-level of abstraction for embedded systems,
    - hardware (ARM big.LITTLE architecture)
  - Continue the study on visualization-assisted interactive debugging
  - · Enrich debugging information generated by compilers
    - work funded by NANO 2017 R&D project

## **Publications**



Kevin Pouget, Marc Pérache, Patrick Carribault, and Hervé Jourdren. User level DB: a debugging API for user-level thread libraries. In *Parallel Distributed Processing, Workshops and Phd Forum (IPDPSW), 2010 IEEE International Symposium on*, pages 1–7, 2010.



Kevin Pouget, Miguel Santana, Vania Marangozova-Martin, and Jean-François Mehaut. Debugging Component-Based Embedded Applications. In *Joint Workshop Map2MPSoC (Mapping of Applications to MPSoCs) and SCOPES (Software and Compilers for Embedded Systems)*, St Goar, Germany, may 2012. Published in the ACM library.



Kevin Pouget, Patricia López Cueva, Miguel Santana, and Jean-François Méhaut. Interactive Debugging of Dynamic Dataflow Embedded Applications. In *Proceedings of the 18th International Workshop on High-Level Parallel Programming Models and Supportive Environments (HIPS)*, Boston, Massachusetts, USA, may 2013. Held in conjunction of IPDPS.



Kevin Pouget, Patricia López Cueva, Miguel Santana, and Jean-François Méhaut. A novel approach for interactive debugging of dynamic dataflow embedded applications. In *Proceedings of the 28th Symposium On Applied Computing (SAC)*, pages 1547–1549, Coimbra, Portugal, apr 2013.

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Thanks for your attention



STMicroelectronics LIG University of Grenoble





# Programming-Model Centric Debugging for Multicore Embedded Systems

## Kevin Pouget

Under the supervision of:

Dr. Miguel Santana, *STMicroelectronics* Prof. Jean-François Méhaut, *CEA/UJF* 

